

Sichere Software durch qualifizierte  
Werkzeuge und normgerechtes  
Entwicklungsvorgehen



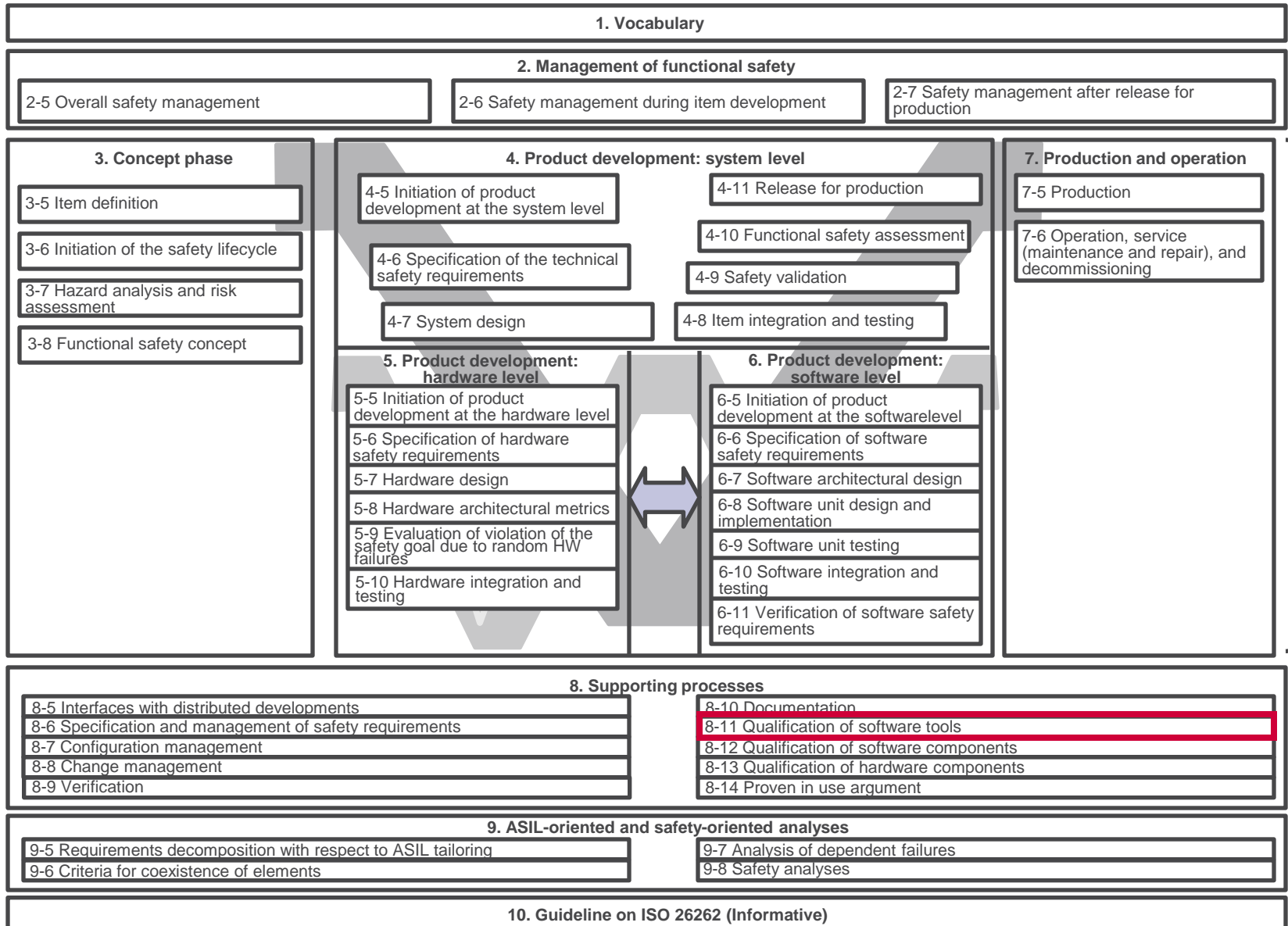
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Automotive Conference · June 2010 · Stuttgart

- New Automotive Standard addressing Functional Safety
  - Derived from IEC 61508:
    - “ISO 26262 is the adaptation of IEC 61508 to comply with needs specific to the application sector of E/E systems within road vehicles.”
- Draft International Standard (DIS) published in July 2009
- Official release planned for 2011
- But already used by OEMs and suppliers

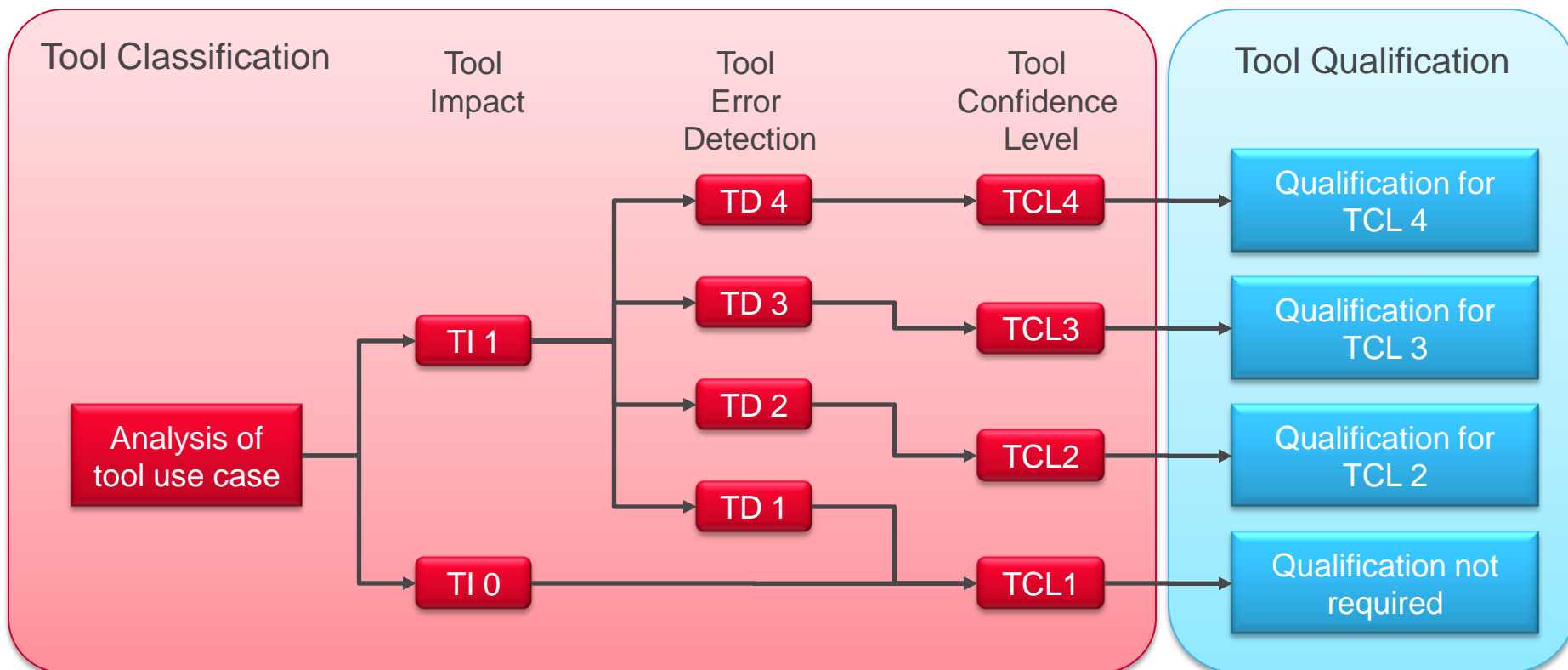




## 11.4.4 Qualification of a software tool

11.4.4.1 A software tool classified at TCL1 needs no qualification measures..

11.4.4.2 To demonstrate that a software tool classified at TCL2, TCL3 or TCL4 fulfils its use cases with the required level of confidence, methods for the qualification of software tools as listed in Table 2, Table 3 and Table 4 shall be applied.



**Table 4 — Qualification of software tools classified TCL2**

Methods		ASIL			
		A	B	C	D
1a	Increased confidence from use	++	++	++	++
1b	Evaluation of the development process	++	++	++	++
1c	Validation of the software tool	+	+	+	+
1d	Development in compliance with a safety standard <sup>a</sup>	+	+	+	+

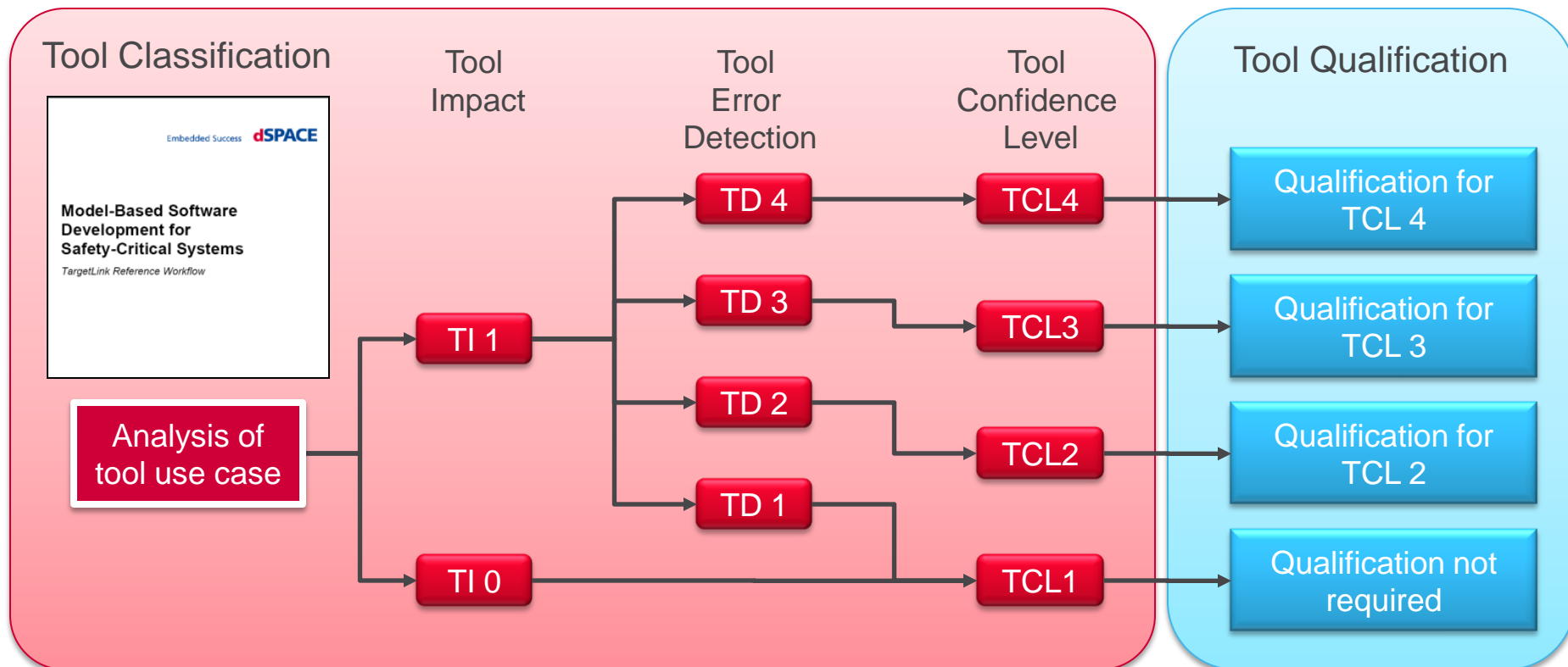
<sup>a</sup> No safety standard is fully applicable to the development of software tools. Instead, a relevant subset of requirements of the safety standard can be selected.

**Table 3 — Qualification of software tools classified TCL3**

Methods		ASIL			
		A	B	C	D
1a	Increased confidence from use	++	++	++	+
1b	Evaluation of the development process	++	++	++	++
1c	Validation of the software tool	+	+	+	++
1d	Development in compliance with a safety standard <sup>a</sup>	+	+	+	++

<sup>a</sup> No safety standard is fully applicable to the development of software tools. Instead, a relevant subset of requirements of the safety standard can be selected.

- Tool Confidence Level (TCL): defines need for qualification and appropriate measures
  - TCL determination based on Reference Workflow



- TargetLink Reference Workflow for the development of safety-related software
  - provides guidance on how to fulfill functional safety requirements with model-based development methods and tools
  - is based on best practices already proven in safety-related projects
  - addresses various aspects relevant for the development of safety-related software with a special focus on verification and validation
  - conforms to IEC 61508 and ISO 26262

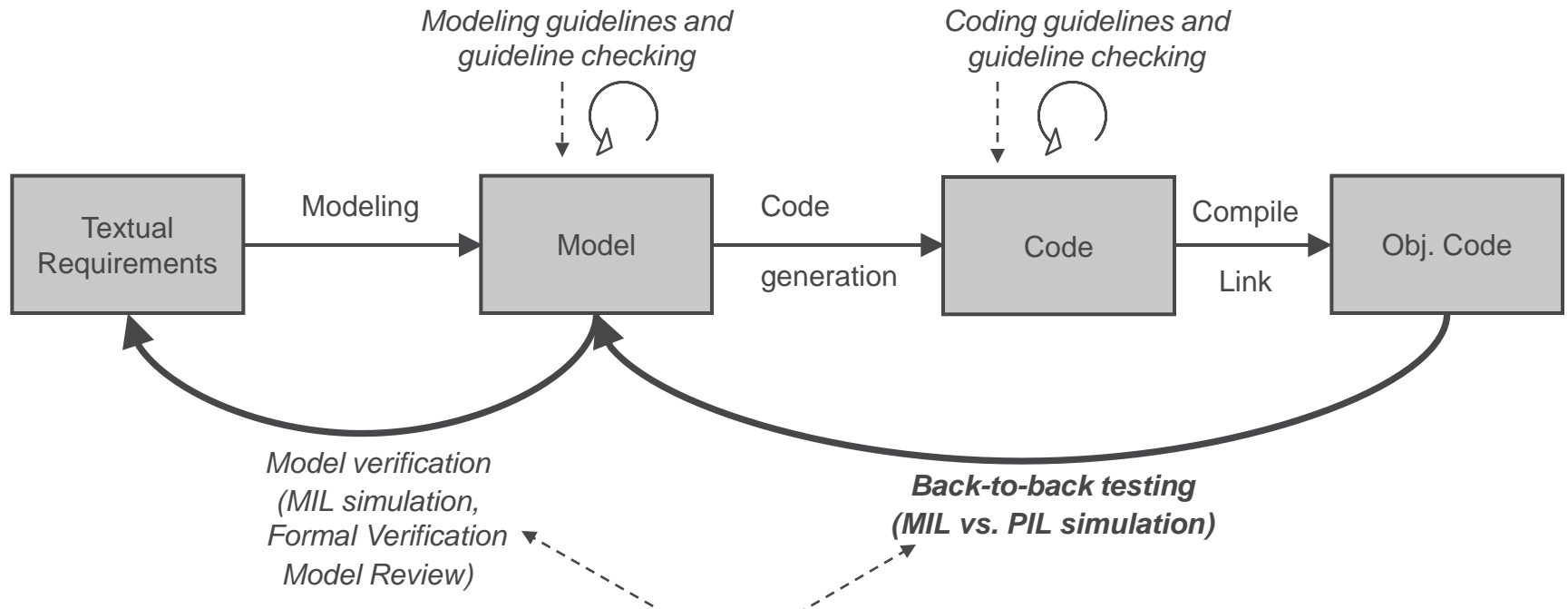
Embedded Success **dSPACE**

## **Model-Based Software Development for Safety-Critical Systems**

*TargetLink Reference Workflow*

Author(s): Michael Beine  
Version: 1.0  
File: TL-ReferenceWorkflow.doc  
Created: 2009-06-16  
Last Modified: 2009-08-24  
Number of Pages: 29

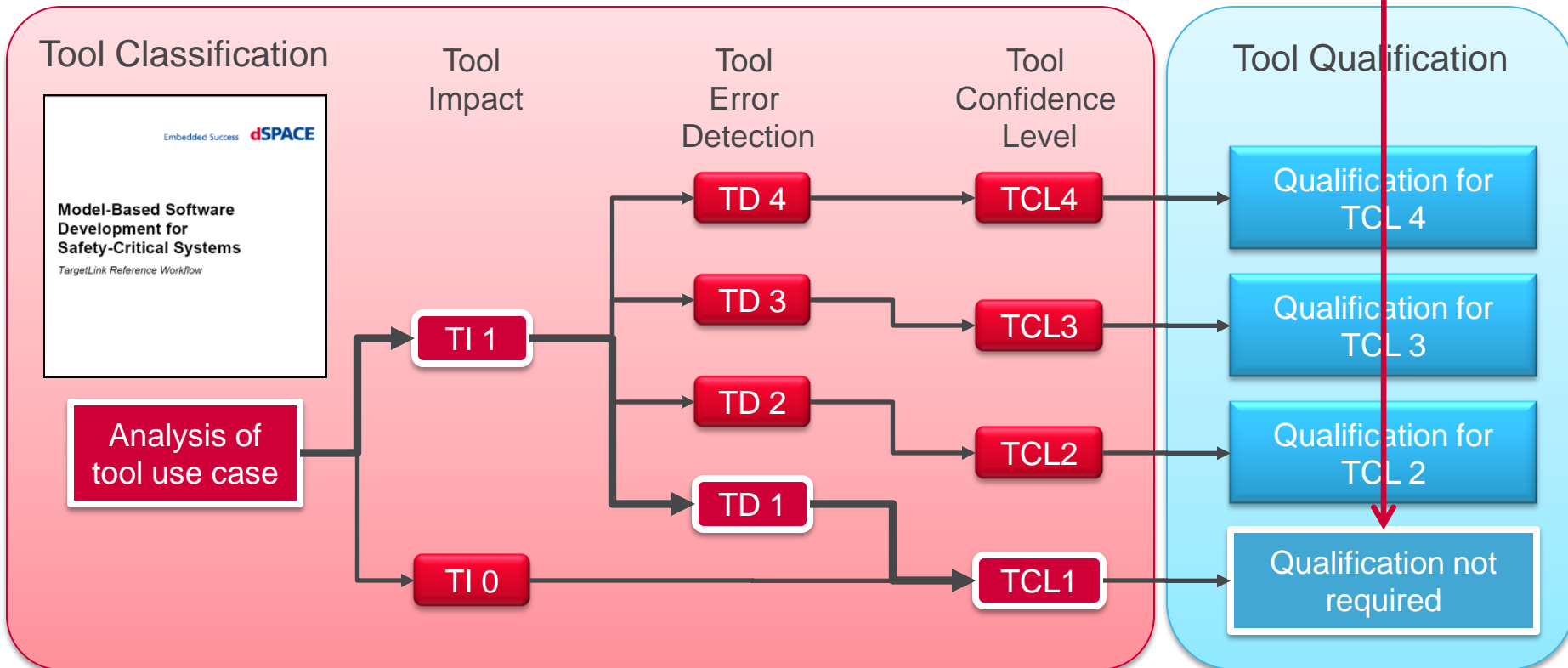
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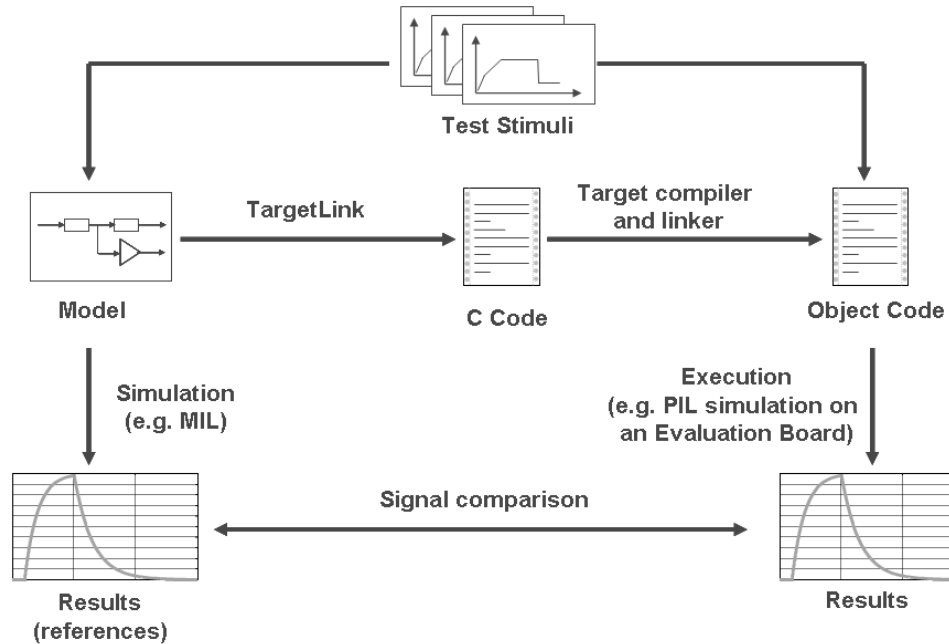
NOTE 4 For model-based development, software unit testing can be carried out at the model level followed by back-to-back tests between the model and the code. The back-to-back tests are used to ensure that the behaviour of the models with regard to the test objectives is equivalent to the automatically-generated code.



- TargetLink
  - TCL based on Reference Workflow
  - “Fit-for-Purpose” Certification



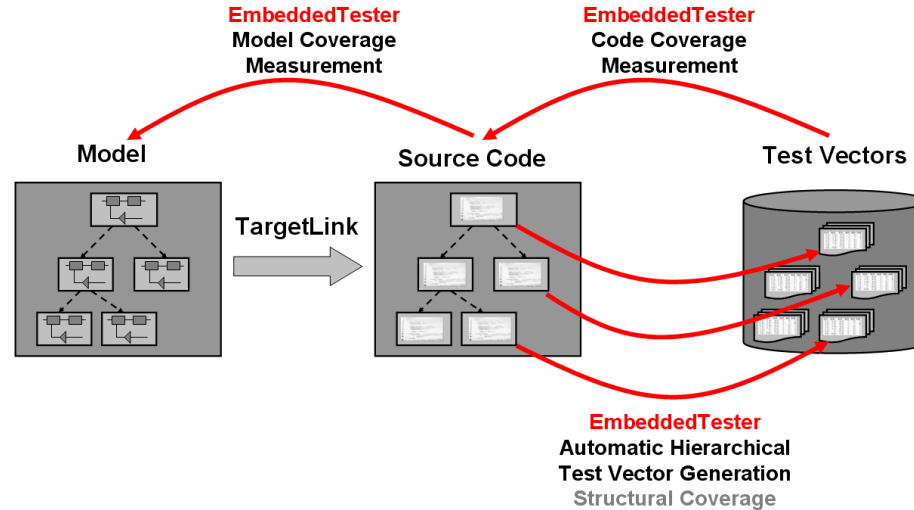
# Code Verification through Automatic Back-to-Back Testing



- Applying “identical” Test Cases both on model and code
  - Taking into account PiL specifics, timing, integer code, ...
- Comparison of output signals wrt slight deviations regarding timing and values

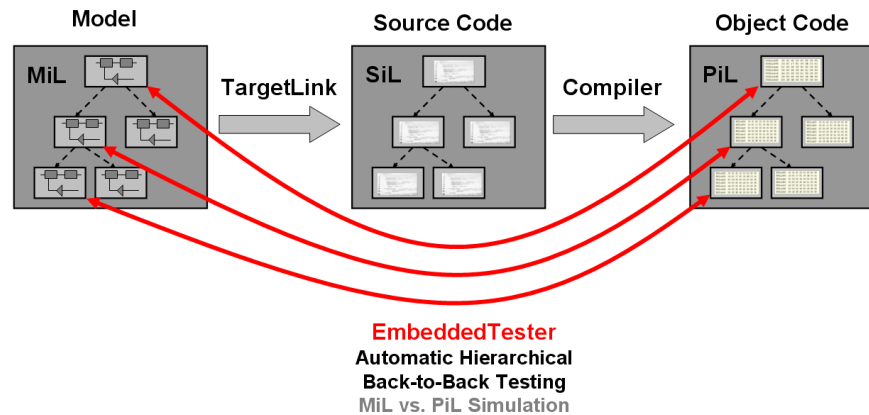
- Developing test cases is a two-stage approach
  - Manual development of test cases based on analysis of requirements
  - Automatic generation of test cases by structural analysis of model and code
- When is a test suite sufficiently powerful?
  - Metrics to determine coverage of code, model and requirements needed
  - Concept *Handling-Rate* for code level combines classical code coverage metrics (Statement, Decision, MCDC) with dead code analysis
    - 100% Handling-Rate regarding a location in the code means
      - either a test case exists contributing to the overall coverage, or
      - the code location under consideration is not executable, under no circumstances (assessment of an experienced engineer is necessary to understand reason!)
  - Leveraging from various algorithms for automatic test case generation (Monte-Carlo, Model-Checking, Bounded Model-Checking)

- Hierarchical...
- ...automatic test case generation
- ... measurement of code and model coverage

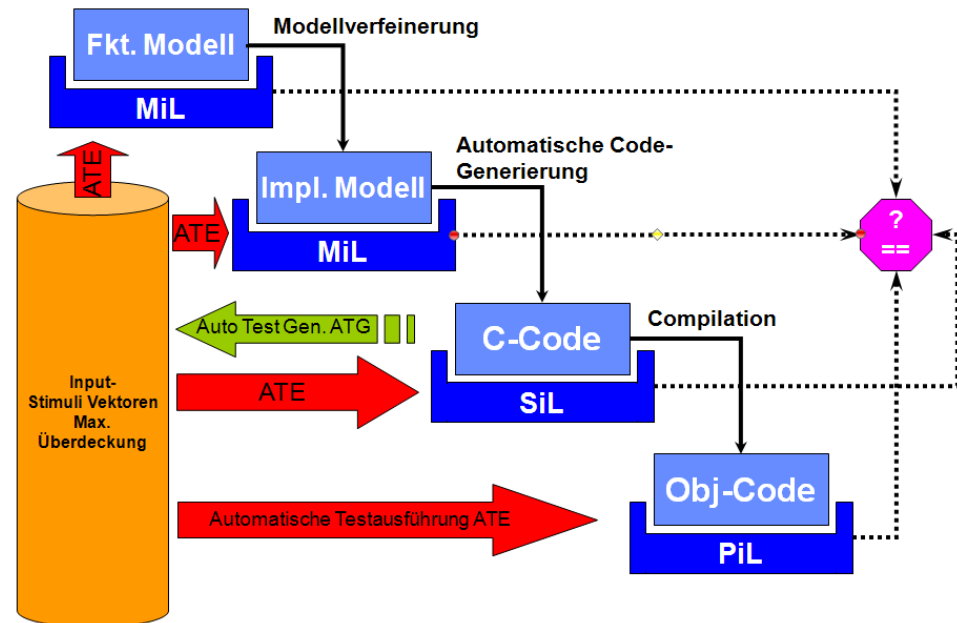


to deal with application complexity when doing structural testing

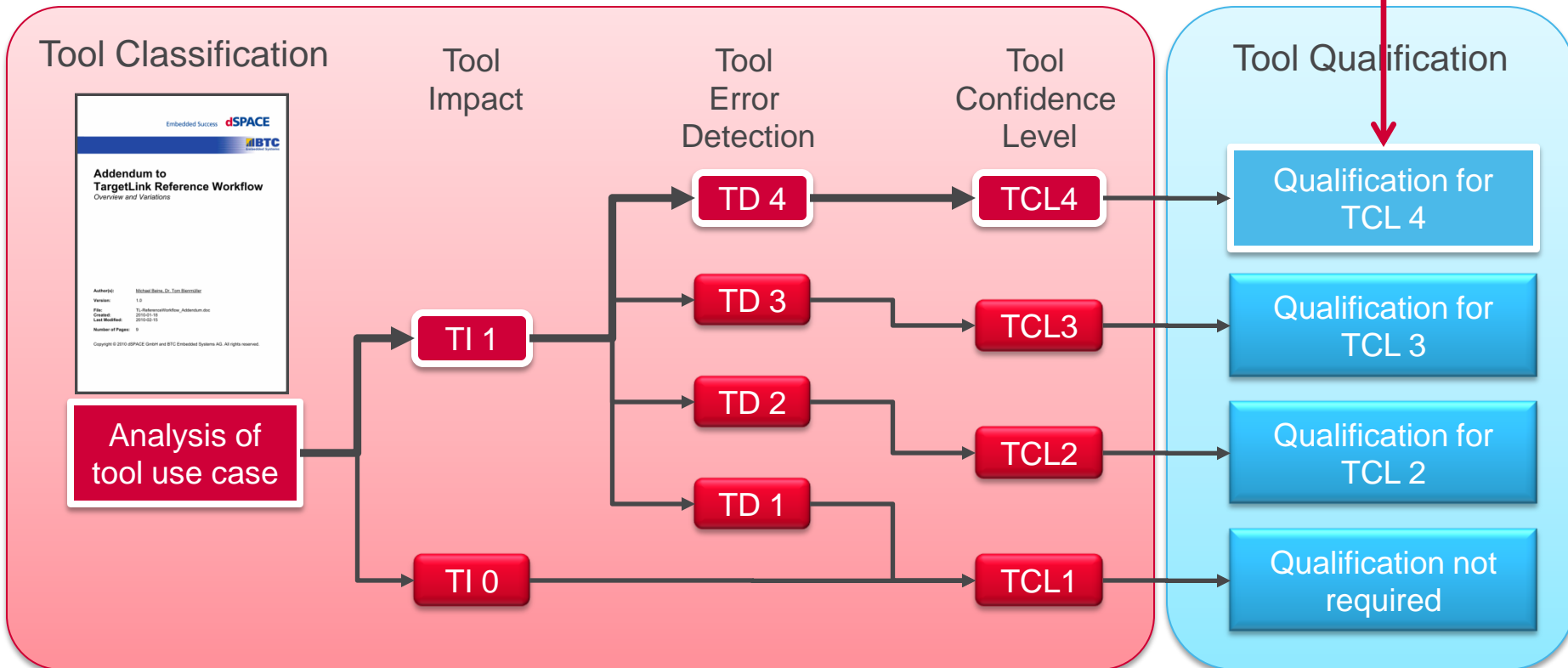
- Hierarchical Back-to-Back Testing



- Automatic test case generation based on the code
  - Automatic test case execution on levels MiL, SiL, PiL
  - Automatic comparison and reporting
  - Automatic measurement of code and model coverage
- 
- Leveraging from the hierarchical approach!
  - Automate as much as possible to be efficient!



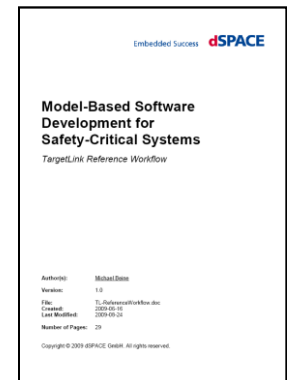
- BTC EmbeddedTester
  - TCL based on Reference Workflow (TCL4)
  - Certification: Validation of Software Tool and Evaluation of Dev. Process





- Model-based development of safety-relevant software is applied in the industry
- TargetLink Reference Workflow based on best practice industry experiences provides guidance on the application of model-based development for safety-critical systems
- ISO 26262 defines a new approach to answer the question for software tool qualification
- Approach has been successfully applied

TargetLink  
Embedded Tester





Thank you for listening!



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